

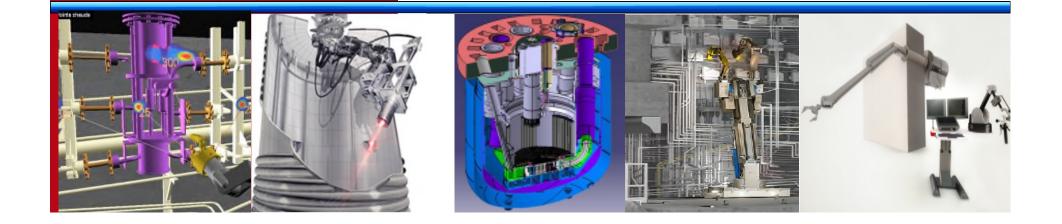


# FRENCH EXPERTISE ON REMOTE-CONTROLLED

# SYSTEMS FOR DECOMMISSIONING

IWAKI, August 6th 2018

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## **DECOMMISSIONING IN FRANCE: 3 OPERATORS WITH GREAT VARIETY OF FACILITIES**



#### ~ 13,5 **B**€ D&D of

Experimental reactors (Gas cooled/PWR/FBR) enrichment & fuel cycle facilities (UP1, APM, etc.)



### ~ 7,5 B€ D&D of

enrichment and **Fuel-cycle** facilities





Challenges similar to 1F in CEA and ORANO Fuel Cycle facilities with joined experience on :

- unexpected situations
- diversity of waste
- high dose rate and contamination (U, Pu and fission products)







Chinon A



St Laurent A



Bugey 1







Chooz A

Brennilis

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# EXAMPLES OF VERY HIGH CONTAMINATION AND RADIOLOGICAL LEVELS – DECOMMISSIONING IN MARCOULE

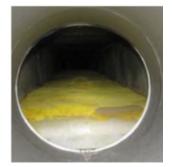
Sludges in tanks up to 300 Gy/h with kilos of Plutonium mixed with Uranium and fission products

- Unexpected after rinsings
- Difficulties to retrieve
- Waste management

Example of legacy waste with fuel debris

Very different chemical and radionuclide compositions; long-lived

Example of vent pipes and corridors contaminated by spent fuel solutions liquors

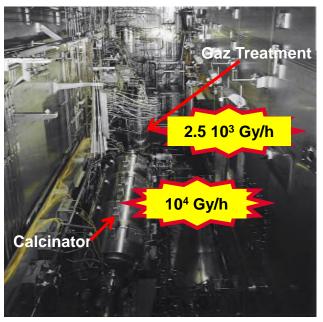




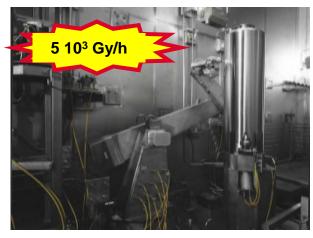


### EXAMPLES OF VERY HIGH CONTAMINATION AND RADIOLOGICAL LEVELS - MAINTENANCE IN LA HAGUE





**Vitrification Cell** 



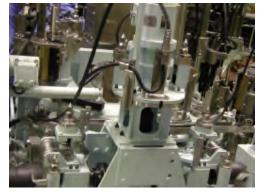
**Automatic Contamination Control** 

- Dispositions and tools ensuring confinement, easing maintenance operation, facilitating decontamination, avoiding contamination spreading, rad proof equipment
- Handling operations and clear vision in hot cells





Vitrification facility hot cells



**Remote removable parts** 



In-cell handling crane (LH ACC) 4

# **LESSONS LEARNED FROM THE 90**s

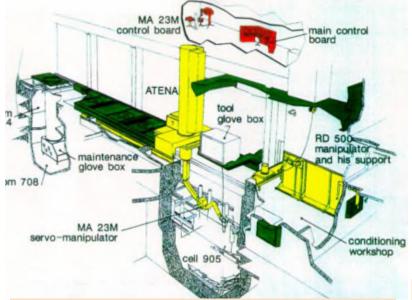
# ATENA = FIRST OPERATIONAL DEMONSTRATOR



1990's computer assisted remote handling

### AT1 reprocessing pilot plant – CEA La Hague

- AT1 shut down in 1979, 2,5 years decontamination
- 4 years from 1990 for dismantling of mechanical hot blind cells with ATENA



- Good process for decontamination and ٠ cutting of equipment and concrete walls
- Very modern concept of telescopic arm ۲
- First demonstration of modern TAO ٠ 2000 control command computerized with force feeback, cartesian mode and graphic supervision



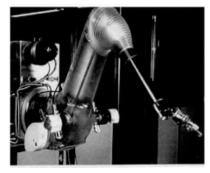
ATENA: multi-jointed holder, equipped with RD 500 type remote manipulator

### But

- Heavy machines •
- Lack of capacity for ٠ decommissioning (500N)
- Could reach equipments only 13 ٠ meters of the cell's entry point

1970's

- Poor reliability ٠
- Problems with some tools
- Not reusable and very expansive •



RD500 developped in the 80's by CEA with Cybernetix

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## UP1 REPROCESSING PLANT – CEA MARCOULE CHEMICAL VERSUS MECHANICAL CELLS

# Ex: Decommissioning of Liquid/liquid extractions Unit (U/PU and fission products)



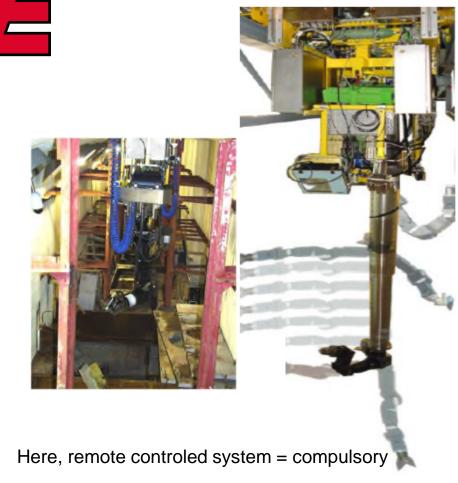
Ex: Decommissioning of spent fuel storage

NO remote controlled operations after decontamination in 2 steps:

1°) through process lines with adequate reagents

2°) decontamination of mixer settlers with decontamination foams





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### DECOMMISSIONING AFTER INCIDENTAL CONTAMINATION BY SPENT FUEL DISSOLUTION LIQUORS IN UP1 MAR200 BUILDING VENTILATION

Former strategy: To use as much as possible «on the shelves » systems and let sub-contractors responsible for the choice of remote controled systems

In 2000: complete project subcontracted at « cost to objective» to a consortium of the best companies of the moment in D&D, but:

- Lack of experience in remote operations
- Minimalist view on operation constraints
- Cutting cadence not well predicted Initial contract broken, time x 4, dosimetry x2



High activity and high contamination



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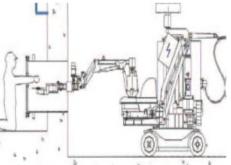


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For transfer of cut pieces







### SEVERAL INCIDENTS AND ACTIVE DEPOSITS LEADING TO DIFFICULTIES FOR RETRIEVAL OF WASTE AND EQUIPMENTS

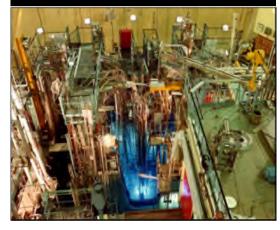
- Incidents happened in 1982 and 1985 in the spent fuel dissolution facility: 460 kg of dry sludge were found in 2011.
- Simple system but numerous inactive tests were necessary for qualification together with need for process equipments and storage for waste management.





### DECOMMISSIONING OF SILOE RESEARCH REACTOR IN GRENOBLE

### 1997: Shut down



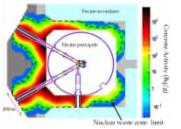


2007: Remote cutting

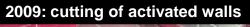
2008



After water draining, dose rate at the bottom of the main pool much higher than expected (activation) => remotecontrolled operations









### 2010: Internal structures out





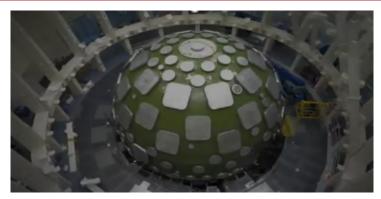


# LONG REACH MANIPULATORS FOR MAINTENANCE OF PLASMA / FUSION RESEARCH FACILITIES

Long reach articulated arm Cea List design & development (2004-2008) , Industrialization by CYBERNETIX in collaboration with CEA List:

- ⇒1<sup>st</sup> introduction in TORE SUPRA tokamak in 2008 (200°C, 10<sup>-5</sup> Pa)
- ⇒ Operational since 2012 at CEA DAM LMJ (Laser Maga Joule) : automatic replacement of protective panels (250 panels /50kg) with 2cm accuracy
  - System with 8 degrees of freedom over 17m and a 100kg payload; 12m horizontal extension, folds back in a 6m mobile casing
  - Tie-in diameter 630mm for complete internal room surface radial access









### SYNTHESIS / LESSONS LEARNED 1. ABOUT METHOD

- Knowledge/ initial state and Definition of final state (radiological but also physical and chemical / waste management)
- Remote systems = Long process often on critical path for D&D operations
- Need for full scale mockups to qualify process and method



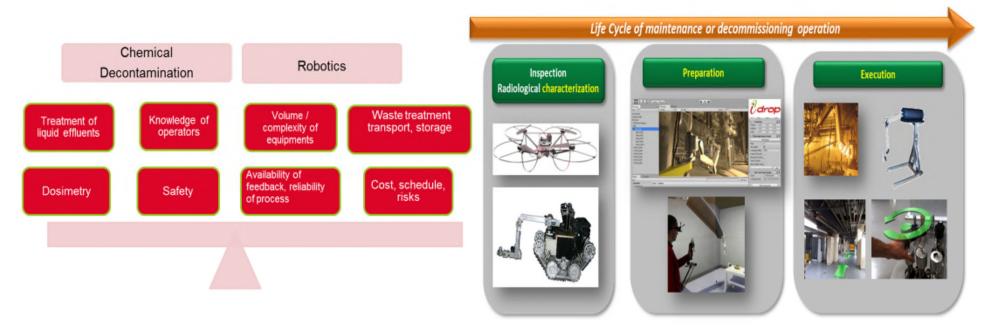
Specific tools for Investigation campaigns



Comparison of scenarios with multiple criteria on global process from investigations to waste routes



«Product lifecycle management » with simulation tools and hazard analysis to validate process and mitigate risks



When dose rates allow to hesitate between remote controled or manual operations, remote operations need to be reliable to offer a valuable gain

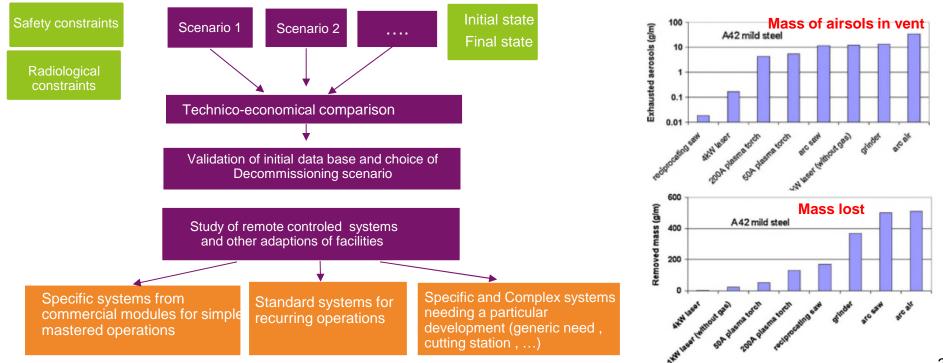
# SYNTHESIS / LESSONS LEARNED 2. ABOUT REMOTE OPERATED SYSTEMS

- •Need to develop industrial systems with higher productivity and improved safety:
  - Lighter, cheaper and more versatile Carriers
  - Manipulator arms with higher payload capacities, more reliability and maintainability, including under agressive decontamination
- •Need to improve tools for segmentation(speed and waste) + changing of tools + umbilical and cables management

Prototypes only for highly recurring operations; for
others, use of proven technologies / bricks + nuclearization

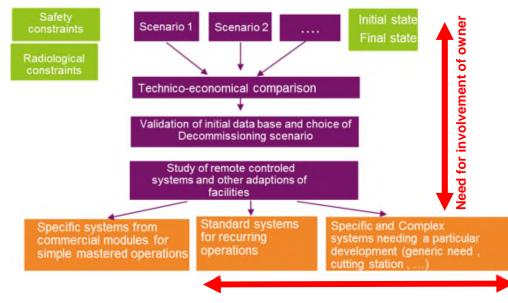
Multi-functional robotic platforms compatible with multiple configurations with easily changed tooling, both for investigation, decontamination, segmentation and retrieval of waste

Tool box to be ready to face unexpected situations / development of laser cutting



### SYNTHESIS / LESSONS LEARNED 3. ABOUT ORGANISATION

- Economy on the material is nothing compared to years of delay with staffing costs
- Concurrency between companies → Hard to deploy feedback and mutualize for optimization
- New skill: Both decommissioning and constructing, adapting technique to operational constraints of the facility



Long and expansive  $\rightarrow$  Need for involvement of owner

Involvement of Owner since engineering studies



Adapted Contracts and interoperability through standards



Integrated teams with operators, project managers, remote controlled specialists and R&D teams

Reluctance to use innovative technologies and search for approved technologies to minimize risks

Need to "Keep it simple" but also to encourage contractors to use more effective/ efficient techniques

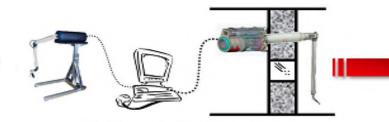
# **SOLUTIONS DEVELOPPED**



### STANDARD REMOTE HANDLING MASTER-SLAVE / «TAO » WITH FORCE FEEBACK **CARTESIAN POSITION**



1970's



1990's computer assisted remote handling



2000's Industrial transfer

- Force feedback master/slave control: improves productivity
- Robotics trajectory control, Virtual Mechanisms
- Cartesian/joint position control: enhances control effectiveness
- Position/force homothetic setting, Gripper pursuit with camera
- 3D graphical supervisor



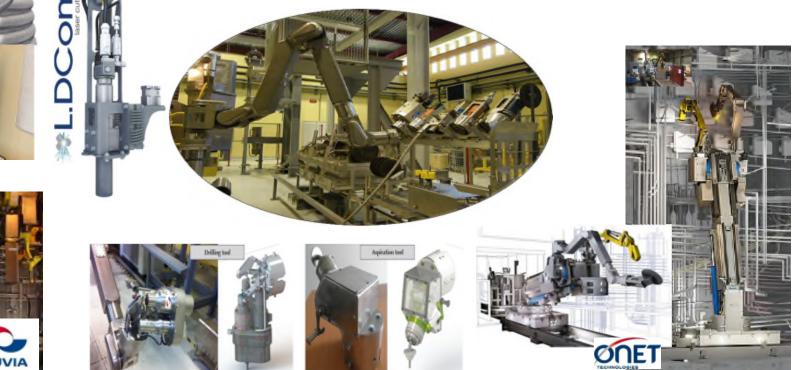
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### REMOTE DISMANTLING FROM R&D ... TO IMPLEMENTATION AT CEA WORKSHOPS





- 4 worshops
- 3 D&D major companies
- 4 configurations (mast, Brokk, crane, rail)







### SOME TOOLS FOR INVESTIGATIONS IN SEVERE ENVIRONMENT

### For visual inspection or sampling



In concrete structures



In decladding pools

For Radiological inspection

NANOPIXCurrently smallest camma camera:268g, 80x51x43mm







High Rad resistance CMOS

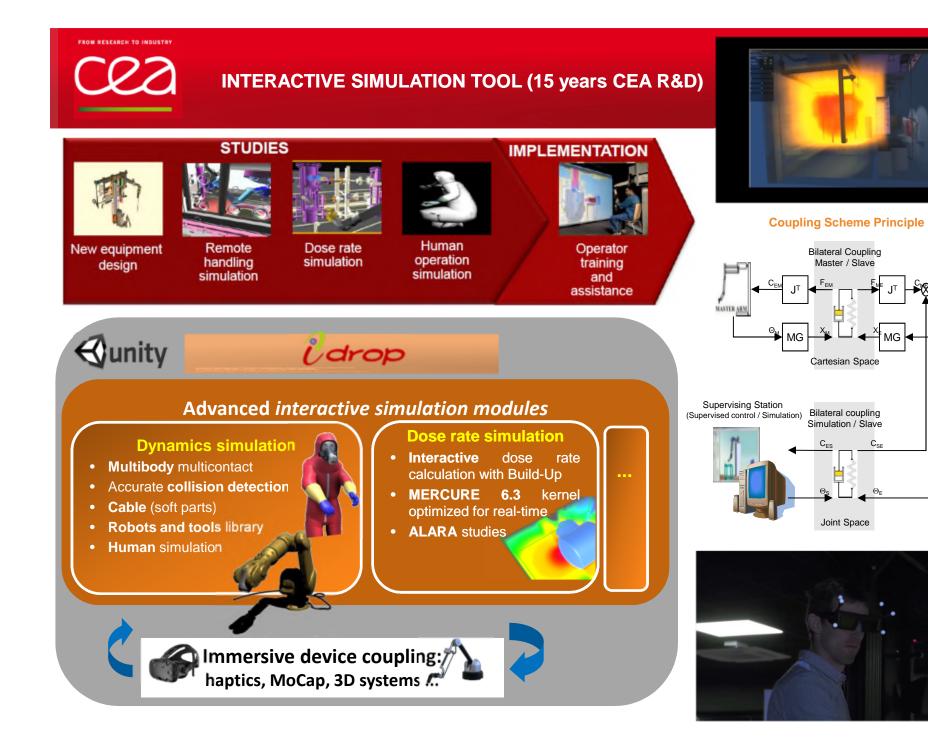


For sampling



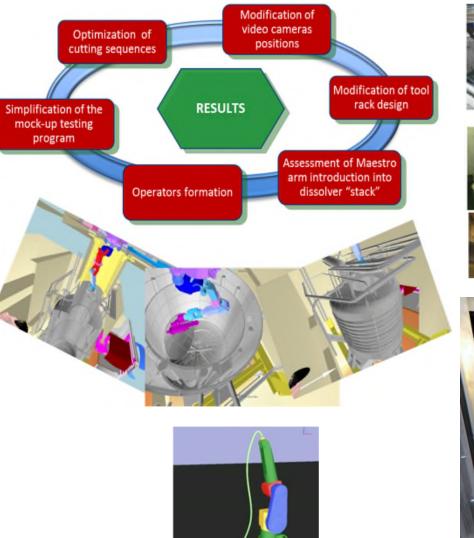


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### COMPLEMENTARITY OF VIRTUAL AND PHYSICAL MOCKUPS TO SECURE PROJECTS Example of UP1 dissolver workshop











# **MORE FUTURISTIC ...SOME ROBOTICS CURRENT TRENDS**

Robotic manipulation for nuclear sorting & segregation



**Dexterous master hand** 

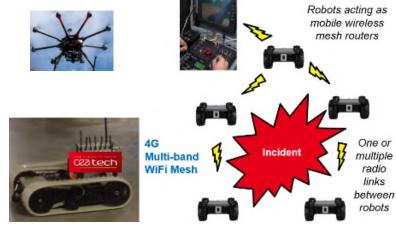


### Visual SLAM + constraints : Assistance to operators





### Wireless network



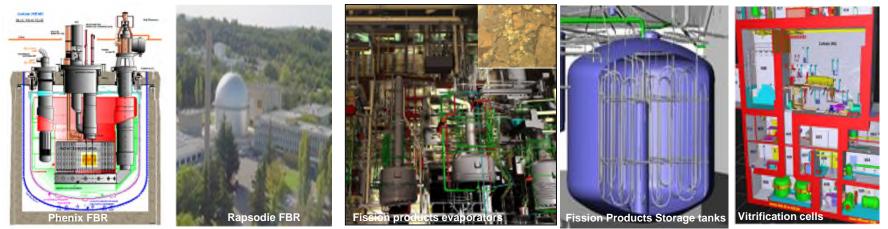


# CONCLUSION

- Lot of similarities with challenges of decommissioning after severe accident : relevance of Fuel cycle Facility operations and D&D experience for Fukushima
- Study of scenarios based on multiples criteria (doses, waste, cost, schedule, etc.) taking into account each step of the process from initial characterization to waste disposal.
- Synergy between operators, project managers, remote controlled specialists and R&D teams
- Progresses in Robotics/ Cobotic in the last 15 years, but still needs for adaptations to increase resistance to radiations and need for qualification for more reliability, flexibility, performance and waste minimization; opportunities for collaboration within the nuclear community:
  - To learn from successes and failures and avoid re-inventing existing proven technologies
  - To share R&I, studies for safety reports, standards for interoperability, pilot operations, etc.



Underwater laser cutting / deep gouging



Example = More than 20 «High activity projects» at CEA in the next 20 years



# NEA WORKSHOP ON THE APPLICATION OF REMOTE AND ROBOTIC SYSTEMS IN DECOMMISSIONING AND WASTE MANAGEMENT

# 30-31 January 2019, Marcoule, France



Exchanges between R&D organisations, waste management and decommissioning operators, national decision makers, regulatory bodies and other interested parties on existing national experience/opinions:

- How to address the main requests of final users
- Determining factors that affect development and implementation: strategic decisions to support the implementation
- Dialogue at the international level to support and facilitate further implementation and to foster harmonized understanding, terminology and approaches through

### DEM2018 – AVIGNON OCTOBER 22/24th INTERNATIONAL CONFERENCE FOCUSED ON D&ER



Thank you for your attention

Hope to see you in Avignon **next October** 





French Alternative Energies and Atomic Energy Commission Centre of Saclay | 91191 Gif-sur-Yvette Cedex

Public industrial and commercial institution | R.C.S Paris B 775 685 019

# ANNEX

# INTERVENTION AFTER AN ACCIDENT: GIE INTRA

- Created in 1988 by CEA, EDF and ORANO
- CONSTITUTE, OPERATE and MAINTAIN a fleet of remotely controlled equipment for interventions in environment radiologically hostile for man.



Creation of an International normalisation commission for remote controled in nuclear in 2016





